

```

TYPE
  glindex = ARRAY [1..ny] OF integer;
  glarray = ARRAY [1..nsi,1..ns] OF real;
  glyarray = ARRAY [1..ny,1..nyk] OF real;
and also declare the global quantities
CONST
  n=41;
VAR
  h,c2,anorm: real; mm,n: integer;
  x: ARRAY [1..m] OF real;
in the main routine. *)
VAR
  temp2,temp: real;
BEGIN
  IF (k = k1) THEN BEGIN
    IF (((n+mm) MOD 2) = 1) THEN BEGIN
      s[3,3+indexv[1]] := 1.0; s[3,3+indexv[2]] := 0.0;
      s[3,3+indexv[3]] := 0.0; s[3,jsf] := y[1,1] END
    ELSE BEGIN
      s[3,3+indexv[1]] := 0.0; s[3,3+indexv[2]] := 1.0;
      s[3,3+indexv[3]] := 0.0; s[3,jsf] := y[2,1] END END
  ELSE IF (k > k2) THEN BEGIN
    s[1,3+indexv[1]] := -(y[3,m]-c2)/(2.0*(mm+1.0));
    s[1,3+indexv[2]] := 1.0; s[1,3+indexv[3]] := -y[1,m]/(2.0*(mm+1.0));
    s[1,jsf] := y[2,m]-(y[3,m]-c2)*y[1,m]/(2.0*(mm+1.0));
    s[2,3+indexv[1]] := 1.0; s[2,3+indexv[2]] := 0.0;
    s[2,3+indexv[3]] := 0.0; s[2,jsf] := y[1,m]-anorm END
  ELSE BEGIN
    s[1,1+indexv[1]] := -1.0; s[1,1+indexv[2]] := -0.5*h;
    s[1,1+indexv[3]] := 0.0; s[1,3+indexv[1]] := 1.0;
    s[1,3+indexv[2]] := -0.5*h; s[1,3+indexv[3]] := 0.0;
    temp := h/(1.0-sqr(x[k]*x[k-1]))*0.25;
    temp2 := 0.5*(y[3,k]*y[3,k-1]) - c2*0.25*sqr(x[k]*x[k-1]);
    s[2,1+indexv[1]] := temp*temp2*0.5;
    s[2,1+indexv[2]] := -1.0*0.5*temp*(mm+1.0)*(x[k]+x[k-1]);
    s[2,1+indexv[3]] := 0.25*temp*(y[1,k]*y[1,k-1]);
    s[2,3+indexv[1]] := s[2,1+indexv[1]];
    s[2,3+indexv[2]] := 2.0*s[2,1+indexv[2]];
    s[2,3+indexv[3]] := s[2,1+indexv[3]]; s[3,1+indexv[1]] := 0.0;
    s[3,1+indexv[2]] := 0.0; s[3,1+indexv[3]] := -1.0;
    s[3,3+indexv[1]] := 0.0; s[3,3+indexv[2]] := 0.0;
    s[3,3+indexv[3]] := 1.0;
    s[1,jst] := y[1,k]-y[1,k-1]-0.5*h*(y[2,k]*y[2,k-1]);
    s[2,jst] := y[2,k]-y[2,k-1]-temp*(x[k]*x[k-1])
      +0.5*(mm+1.0)*(y[2,k]*y[2,k-1]-temp2*0.5*(y[1,k]*y[1,k-1]));
    s[3,jst] := y[3,k]-y[3,k-1] END
  END;

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Chapter 17. Introduction to Partial Differential Equations

Relaxation Methods for Boundary Value Problems

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PROCEDURE sor(a,b,c,d,e,f: gljmax; VAR u: gljmax;
  jmax: integer; rjac: double);
(* Programs using routine SOR must define the type
TYPE
  gljmax = ARRAY [1..jmax,1..jmax] OF double;
in the main routine. *)
LABEL 99;
CONST

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maxits=1000; eps=1.0e-5; zero=0.0; half=0.5; qtr=0.25; one=1.0;
n,l,j: integer; resid,omega,anormf,anorm: double;
BEGIN
  anormf := zero;
  FOR j := 2 TO jmax-1 DO BEGIN
    anormf := anormf+abs(f[j,1]) END END;
  omega := one;
  FOR n := 1 TO maxits DO BEGIN
    anorm := zero;
    FOR j := 2 TO (jmax-1) DO BEGIN
      FOR l := 2 TO (jmax-1) DO BEGIN
        resid := a[j,l]*u[j+1,l]+b[j,l]*u[j-1,l]
          +c[j,l]*u[j,l+1]+d[j,l]*u[j,l-1]
          +e[j,l]*u[j,l]-f[j,l]; anorm := anorm+abs(resid);
        u[j,l] := u[j,l]-omega*resid/e[j,l] END END END;
    IF (n = 1) THEN BEGIN
      omega := one/(one-half*sqr(rjac)) END
    ELSE BEGIN
      omega := one/(one-qtr*sqr(rjac)*omega) END;
    IF ((n > 1) AND (anorm < (eps*anormf))) THEN GOTO 99
  END;
  writeln('pause in routine SOR');
  writeln('too many iterations'); readln;
99: END;

PROCEDURE adi(a,b,c,d,e,f,g: gljmax; VAR u: gljmax;
  jmax,k: integer; alpha,beta,eps: double);
(* Programs using routine ADI must define the type
TYPE
  gljmax = ARRAY [1..jmax,1..jmax] OF double;
in the main routine. *)
LABEL 99;
CONST
  jj=60; kk=6; (* nrr=2 to the power (kk-1) *)
  maxits=100; zero=0.0; two=2.0; half=0.5;
  gljarray = ARRAY [1..j] OF double;
VAR
  i,nr,nits,next,n,l,kits,ki,j,twopwr: integer;
  rfac,resid,disc,anorm,anorm,ab: double; aa,bb,cc,rr,uu: gljarray;
  psi: ARRAY [1..j,1..j] OF double;
  alph,bet: ARRAY [1..kk] OF double;
  r: ARRAY [1..nrr] OF double;
  s: ARRAY [1..nrr,1..kk] OF double;
PROCEDURE tridag(a,b,c,r: gljarray; VAR u: gljarray; n: integer);
(* This is a double precision version of TRIDAG for use with ADI,
  which defines the constant j and the type gljarray. *)
VAR
  j: integer; bet: double; gam: gljarray;
BEGIN
  IF (b[1] = 0.0) THEN BEGIN
    writeln('pause 1 in TRIDAG'); readln END;
    bet := b[1]; u[1] := r[1]/bet;
    FOR j := 2 TO n DO BEGIN
      gam[j] := c[j-1]/bet; bet := b[j]-a[j]-gam[j];
      IF (bet = 0.0) THEN BEGIN
        VAR
          j: integer; bet: double; gam: gljarray;
        BEGIN
          IF (b[1] = 0.0) THEN BEGIN
            writeln('pause 1 in TRIDAG'); readln END;
            bet := b[1]; u[1] := r[1]/bet;
            FOR j := 2 TO n DO BEGIN
              gam[j] := c[j-1]/bet; bet := b[j]-a[j]-gam[j];
              IF (bet = 0.0) THEN BEGIN

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Operator Splitting Methods and ADI

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writeln('pause 2 in TRIDAG'); readln END;
u[j] := (r[j]-a[j]*u[j-1])/bet END;
FOR j := n-1 DOWNTO 1 DO u[j] := u[j]-gam[j+1]*u[j+1]
END;
BEGIN
IF (jmax > jj) THEN BEGIN
writeln('Pause in routine ADI - increase jj'); readln
END;
IF (k > (kk-1)) THEN BEGIN
writeln('Pause in routine ADI - increase kk'); readln
END;
k1 := k+1; nr := 1;
FOR i := 1 TO k DO nr := 2*nr;
alpha[1] := alpha; bet[1] := beta;
FOR j := 1 TO k DO BEGIN
alpha[j+1] := sqrt(alpha[j]*bet[j]); bet[j+1] := half*(alpha[j]*bet[j])
END;
s[1,1] := sqrt(alpha[k1]*bet[k1]);
FOR j := 1 TO k DO BEGIN
ab := alpha[k1-j]*bet[k1-j]; twopr := 1;
FOR i := 1 TO (j-1) DO twopr := 2*twopr;
FOR n := 1 TO twopr DO BEGIN
disc := sqrt(sqr(s[n,j])-ab); s[2*n-1,j+1] := s[n,j]+disc;
s[2*n-1,j+1] := ab/s[2*n,j+1] END END;
FOR n := 1 TO nr DO r[n] := s[n,k1];
anorm := zero;
FOR j := 2 TO (jmax-1) DO BEGIN
FOR i := 2 TO (jmax-1) DO BEGIN
anorm := anorm+abs(g[j,i]); psi[j,1] := -d[j,1]*u[j,1-1]
+(r[i]-e[j,1])*u[j,1]-f[j,1]*u[j,1+1] END END;
nite := maxite DIV nr;
FOR kits := 1 TO nite DO BEGIN
FOR n := 1 TO nr DO BEGIN
IF (n = nr) THEN next := 1 ELSE next := n+1;
rfact := r[n]*r[next];
FOR i := 2 TO (jmax-1) DO BEGIN
FOR j := 2 TO jmax-1 DO BEGIN
aa[j-1] := a[j,1]; bb[j-1] := b[j,1]+r[n];
cc[j-1] := c[j,1]; rr[j-1] := psi[j,1]-g[j,1] END;
tridag(aa,bb,cc,rr,uu,jmax-2);
FOR j := 2 TO (jmax-1) DO BEGIN
psi[j,1] := -psi[j,1]+two*r[n]*uu[j-1] END END;
FOR i := 2 TO (jmax-1) DO BEGIN
FOR j := 2 TO (jmax-1) DO BEGIN
aa[1-1] := d[j,1]; bb[1-1] := e[j,1]+r[n];
cc[1-1] := f[j,1]; rr[1-1] := psi[j,1] END;
tridag(aa,bb,cc,rr,uu,jmax-2);
FOR i := 2 TO (jmax-1) DO BEGIN
u[j,1] := uu[1-1]; psi[j,1] := -psi[j,1]+rfact*uu[1-1]
END END END;
anorm := zero;
FOR j := 2 TO (jmax-1) DO BEGIN
FOR i := 2 TO (jmax-1) DO BEGIN
resid := a[j,1]*u[j-1,1]+(b[j,1]+e[j,1])*u[j,1]
+c[j,1]*u[j+1,1]+d[j,1]*u[j,1-1]+f[j,1]*u[j,1+1]+g[j,1];
anorm := anorm+abs(resid) END END;
IF (anorm < (eps*anorm)) THEN GOTO 99
END;
writeln('Pause in routine ADI - too many iterations');
99: END;

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Table of Program Dependencies

The following table lists, in alphabetical order, all the routines in *Numerical Recipes*. The section number in which the routine is listed occurs next, followed by the list of routines (if any) that are necessary for the execution of the routine first named. Note that the dependency list is complete: you do not need to look at other table entries for the additional dependencies of routines listed on the right-hand side of a given entry.

ADI	(§17.6)	TRIDAG	
AMEBA	(§10.4)	LINK	
ANNEAL	(§10.9)	FLMOON	JULDAY
AVEVAR	(§13.4)		
BADLUK	(§1.1)		
BALANC	(§11.5)		
BCUCOF	(§3.6)		
BCUINF	(§3.6)		
BESSI	(§6.5)		
BESSIO	(§6.5)		
BESSJ	(§6.5)		
BESSJO	(§6.4)		BESSJ1
BESSJ1	(§6.4)		
BESSK	(§6.5)		BESSK1
BESSKO	(§6.5)		BESSIO
BESSK1	(§6.5)		BESSY1
BESSY	(§6.4)		BESSJO
BESSYO	(§6.4)		
BESSY1	(§6.4)		
BETA	(§6.1)		GAMMLN
BETACF	(§6.3)		BETACF
BETAI	(§6.3)		FACTLN
BICO	(§6.1)		
BKSUB	(§16.3)		
BHLDEV	(§7.3)		RAN1
BRENT	(§10.2)		
BSSTEP	(§15.4)		MWID
CALDAT	(§1.1)		
CEL	(§6.7)		
CHDER	(§5.7)		
CHEBEV	(§5.6)		